Optimal control of the motion of a viscous heat-conducting gas using physics-informed neural networks

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OPTIMAL CONTROL OF THE MOVEMENT OF VISCOUS HEAT-CONDUCTING GAS USING NEURAL NETWORKS

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The optimal control problem for a system of gas dynamics equations in the onedimensional case is considered. The speed of the medium at the initial moment of time and at the right end of the boundary is selected as control. A mathematical model describing the movement of a viscous heat-conducting gas in the interval (0, 1), together with the boundary and initial conditions, can be described by the following system of equations:

$$\rho \left[u_t + \operatorname{Sh} u u_x \right] = \frac{\operatorname{Sh}}{\operatorname{Re}} u_{xx} - \operatorname{Sh} k \ (\rho \theta)_x = 0, \quad \rho_t + \operatorname{Sh} \ (u \rho)_x = 0, \tag{1}$$

$$\rho \left[\theta_t + \operatorname{Sh} u\theta_x\right] = \frac{\operatorname{Sh}}{\operatorname{Pe}} \theta_{xx} + \frac{\operatorname{Sh}}{\operatorname{Re}} \frac{\pi}{k} \left(u_x\right)^2 - \operatorname{Sh} \pi \rho \theta u_x = 0, \qquad (2)$$

$$u|_{t=0} = u_0(x), \ \rho|_{t=0} = \rho_0(x), \ \theta|_{t=0} = \theta_0(x),$$
 (3)

$$u|_{x=0} = u_1(t), \quad \rho|_{x=0} = \rho_1(t), \quad \theta|_{x=0} = \theta_1(t), \quad u|_{x=1} = u_2(t), \quad \theta|_{x=1} = \theta_2(t), \quad (4)$$

where u, ρ, θ are unknown gas speed, density and temperature, $u_t = \partial u/\partial t, u_x = \partial u/\partial x, u_{xx} = \partial^2 u/\partial x^2, u_0, \rho_0, \theta_0, u_1, \rho_1, \theta_1, u_2, \theta_2$ – given functions, Sh, Pe, Re, π , k – dimensionless coefficients.

The optimal control problem comes down to minimizing the following quality functional:

$$J(\mathbf{v}) = J_f(\mathbf{s}) + \alpha_1 \int_0^1 |u_{0x}|^2 \, dx + \alpha_2 \int_0^1 |u_{2t}|^2 \, dt, \tag{5}$$

where $\mathbf{s} = \{u, \rho, \theta\}$ — state of the system (1)–(4), $\mathbf{v} = \{u_0, u_2\}$ — control, $\alpha_1 > 0$, $\alpha_2 > 0$, $J_f(\mathbf{s})$ — lower semicontinuous functional.

The correctness of the optimal control problem (1)-(5) was studied in the work [1].

Based on the neural network approximation of unknown functions, an algorithm has been developed for finding an approximate solution to the extremal problem (5) for various target functionals $J_f(\mathbf{s})$. The work was carried out within the state assignment of the Institute of Applied Mathematics, FEB RAS (No. 075-01290-23-00) and with the support of the Ministry of Science and Higher Education of the Russian Federation (project No. 075-02-2023-946)

СПИСОК ЛИТЕРАТУРЫ

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