

An interval approach to recognition of numerical matrices

Alexander Prolubnikov

Omsk State University

e-mail: `a.v.prolubnikov@mail.ru`

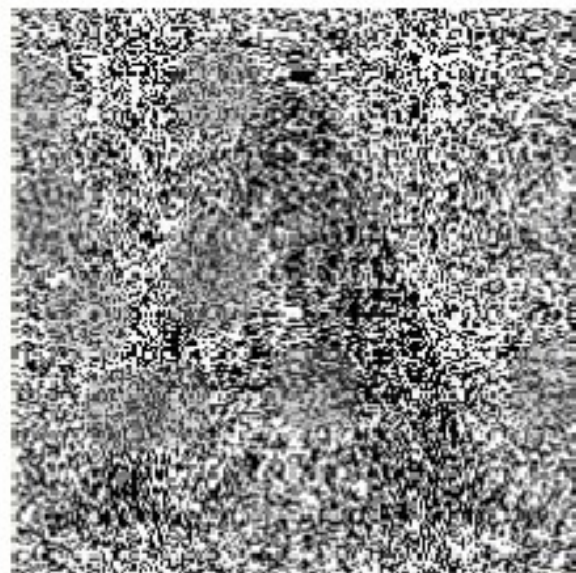
The statement of the problem

- $\{\mathcal{A}^{(k)}\}_{k=1}^N$ — pattern matrices, $a_{ij}^{(k)} \in \mathbb{R}$
- \mathcal{A} is obtained in the process of noising from $\mathcal{A}^{(p)}$
 p is unknown
- it's known that matrices elements
may be changed in the intervals

$$[a_{ij}^{(k)} - \Delta, a_{ij}^{(k)} + \Delta], \quad \Delta > 0$$

We must define p (noised pattern matrix $\mathcal{A}^{(p)}$)

A E



Constructing of heuristics

We associate the input matrices with interval matrices:

$$\{\mathcal{A}^{(k)}\}_{k=1}^N \rightarrow \{\mathbf{A}^{(k)}\}_{k=1}^N$$

$$\mathbf{A}^{(k)} = (\mathbf{a}_{ij}^{(k)}):$$

$$\mathbf{a}_{ij}^{(k)} = [\min\{a_{ij}^{(k)}, a_{ij}\}, \max\{a_{ij}^{(k)}, a_{ij}\}],$$

where $a_{ij}^{(k)}$ are elements of pattern matrix $\mathcal{A}^{(k)}$,
 a_{ij} are elements of recognized matrix \mathcal{A}

Elements of $\mathbf{A}^{(k)}$ are intervals,

which characterise changes of elements of pattern matrix $\mathcal{A}^{(k)}$
needed to obtain recognized matrix \mathcal{A}

Constructing of heuristics

Construct the systems of interval linear equations:

$$\mathbf{A}^{(k)}x = b, \quad b \in \mathbb{R}^n$$

Suggestion: the lesser the variation of solutions of systems of linear equations, which gives the interval system $\mathbf{A}^{(k)}x = b$, the likely the recognized matrix \mathcal{A} is obtained from $\mathcal{A}^{(k)}$

The variation of solutions of systems of linear equations, which gives $\mathbf{A}^{(k)}x = b$, is measured by

Lebesgue measure of united solution set $\Xi(\mathbf{A}^{(k)}, b)$:

$\mu(\Xi(\mathbf{A}^{(k)}, b))$ is depends on:

- mutual disposition of elements of the matrices.
- It depends continuously on their changes.

The selection of the right-hand side vector of the system

$$\mathbf{A}^{(k)}x = b$$

- the right-hand side vector is a real vector

It gives more precise enclosure of united solution set

because such selection decreases the distance between $\Xi(\mathbf{A}^{(k)}, b)$ and its interval hull $\square\Xi(\mathbf{A}^{(k)}, b)$

- if $b = e = (1, \dots, 1)^\top$, then all of the elements of input matrix accounting at equal measure at the process of recognition

Thus, we consider the following systems of interval linear equations:

$$\mathbf{A}^{(k)}x = e$$

Computational complexity of the recognition

$$\Xi^{(k)} \stackrel{\text{def}}{=} \Xi(\mathbf{A}^{(k)}, e)$$

The problem of calculating of $\mu(\Xi^{(k)})$ has an exponential complexity

$\mathbf{X}^{(k)}$ is an approximation of $\square\Xi^{(k)}$

$\mathbf{X}^{(k)}$ is a box: $\mathbf{X}^{(k)} = ([\underline{x}_1^k, \overline{x}_1^k], \dots, [\underline{x}_n^k, \overline{x}_n^k])^\top$,

such that $\square\Xi^{(k)} \subseteq \mathbf{X}^{(k)}$

$$\mu(\mathbf{X}^{(k)}) = (\overline{x}_1^k - \underline{x}_1^k) \cdot \dots \cdot (\overline{x}_n^k - \underline{x}_n^k)$$

If *Encl* is some algorithm for enclosing of united solution set, then

$$C(N, n, \text{Encl}) = O(N \cdot C_{\text{Encl}}(n))$$

If $C_{\text{Encl}}(n) = O(n^2)$, then we have an algorithm

with lowest order of complexity

for algorithms of solution of the considered problem.

Modifications of the input matrices

Interval of change:

$$[a_{ij}^{(k)} - \Delta, a_{ij}^{(k)} + \Delta], \Delta > 0$$

Modification:

$$a_{ij} := a_{ij} + v$$

$$a_{ij}^{(k)} := a_{ij}^{(k)} + v$$

$$(v > 0)$$

As a result:

decreasing of the ratio:

$$\frac{\Delta}{|a_{ij}^{(k)}|} \rightarrow \frac{\Delta}{|a_{ij}^{(k)} + v|}$$

if the ratio $\Delta/|a_{ij}^{(k)}|$ is small enough then recognition is possible

Modifications of the input matrices

$$1) \mathbf{A}^{(k)} := \mathbf{A}^{(k)} + v\mathbf{E}, \quad \mathbf{E}_{ij} = [1, 1], \quad i, j = \overline{1, n}$$

$$2) \mathbf{A}^{(k)} := \mathbf{A}^{(k)} + \mathbf{D}, \quad \mathbf{D} \text{ is diagonal interval matrix}$$

$$\mathbf{D}_{ii} = [D, D]$$

$$D^{(k)} = 2 \max_{1 \leq i \leq n} \sum_{j \neq i} |(\mathbf{A}^{(k)})_{ij}|, \quad D = \max_{1 \leq k \leq N} D^{(k)}$$

As a result:

$\mathbf{A}^{(k)}$ are H -matrices

We may use interval Gauss-Seidel method for enclosing $\square \Xi^{(k)}$

The initial approximation:

$$\text{box } ([-B, B], \dots, [-B, B])^\top, \quad B = 1/[v(n-1)]$$

The algorithm

Input: $\{\mathcal{A}^{(k)}\}_{k=1}^N$ and \mathcal{A} .

Output: Index p (matrix $\mathcal{A}^{(p)} \in \{\mathcal{A}^{(k)}\}_{k=1}^N$)

1. Construct matrices $\{\mathbf{A}^{(k)}\}_{k=1}^N$.

2. Using *Encl* calculate $\mathbf{X}^{(k)}$, $k = \overline{1, N}$.

($\mathbf{X}^{(k)}$ are enclosures of $\Xi^{(k)}$)

3. Chose p such that $\mu(\mathbf{X}^{(p)}) = \min_{1 \leq k \leq N} \mu(\mathbf{X}^{(k)})$.

p is a result of recognition

Total computational complexity:

$Encl = GS,$

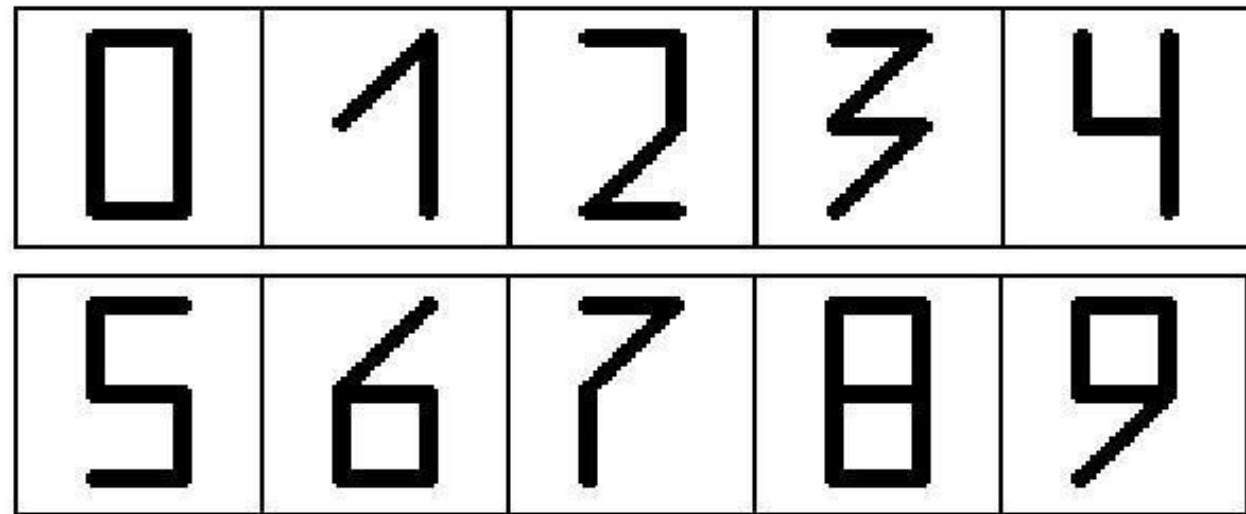
$$\underline{C(N, n, GS) = O(N \cdot N_{GS} \cdot n^2)}$$

($N_{GS} = 20$)

Computational experiment

Pattern images

20×20 , 35×35 ,
 50×50 and 100×100
pixels resolution



$$a_{ij}^{(k)} = \begin{cases} c_1, & \text{if pixel in } ij \text{ position is white,} \\ c_2, & \text{if pixel in } ij \text{ position is black} \end{cases}$$

- black and white images: $c_1 = 0$ and $c_2 = 1$,
- greyscale images: $c_1, c_2 \in [0, 255]$

Level of noise $Q \in [0, 100]$ (%)

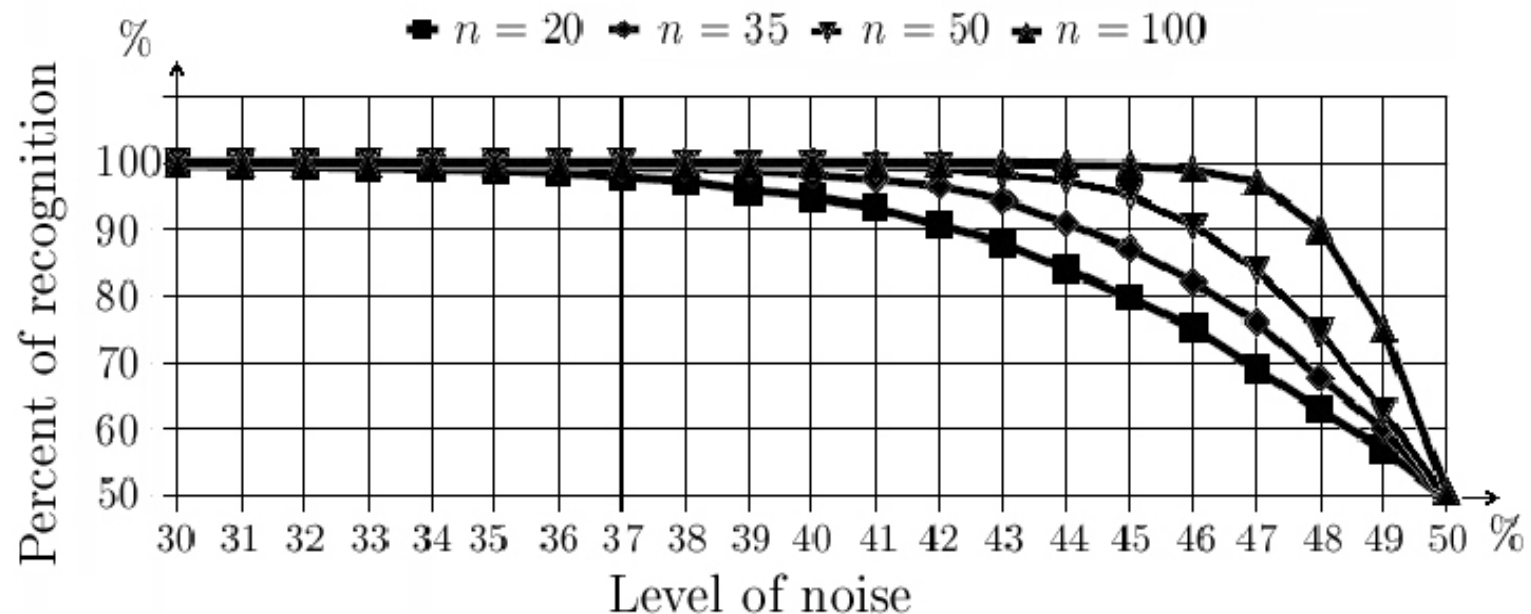
Percent of recognition

$$P = \frac{\text{number of correct recognition}}{\text{number of trials}} \times 100$$

Computational experiment

Q	31	32	33	34	35	36	37	38	39	40
$n = 20$	99.57	99.6	99.37	99.19	99	98.56	98	97.27	95.97	94.96
$n = 35$	99.9	99.97	99.97	99.84	99.83	99.71	99.47	99.36	99.02	98.31
$n = 50$	100	100	99.99	99.98	99.97	99.99	99.93	99.89	99.82	99.74
$n = 100$	100	100	100	100	100	100	100	100	100	100
Q	41	42	43	44	45	46	47	48	49	50
$n = 20$	93.32	90.67	88.07	84.1	79.87	75.28	69.16	63.06	57.02	49.72
$n = 35$	97.52	96.55	94.46	91	87.22	82.18	76.16	67.86	60.13	49.41
$n = 50$	99.51	99.27	98.36	97.29	95.23	90.6	83.99	74.61	62.69	49.86
$n = 100$	100	99.98	99.97	99.86	99.68	99.08	97.23	99.08	75.09	50.68

Percent of recognition for level of noise from 31% up to 50%, $c_1 = 0$, $c_2 = 1$



Computational experiment

Comparison of recognition efficiency

of the presented heuristics with recognition efficiency of minimization of the distance $\rho(\mathcal{A}, \mathcal{A}^{(k)})$

$$\rho(\mathcal{A}, \mathcal{A}^{(k)}) = \sqrt{\sum_{i=1}^n \sum_{j=1}^n \left(a_{ij} - a_{ij}^{(k)} \right)^2}$$

$$\rho(\mathcal{A}, \mathcal{A}^{(1)}) < \rho(\mathcal{A}, \mathcal{A}^{(2)}),$$

$$\text{but } |a_{ij} - a_{ij}^{(2)}| < |a_{ij} - a_{ij}^{(1)}|$$

for majority of ij positions of this matrices

Computational experiment

Comparison of recognition efficiency

of the presented heuristics with recognition efficiency of
minimization of the distance $\rho(\mathcal{A}, \mathcal{A}^{(k)})$

S is percent of the trials

in which presented approach gives a recognition

and minimizing of $\rho(\mathcal{A}, \mathcal{A}^{(k)})$ doesn't give a recognition

$S, \%$	0	5.4	7.4	16.2	23.5
$P, \%$	100	99.93	99.79	99.72	99.81
Δ	10	25	50	75	100

Values of S when level of noise is equal to 44%, $c_1 = 110$, $c_2 = 120$

$S, \%$	22.8	37.5	47.3	46.4	46.4
$P, \%$	99.71	99.6	99.8	99.72	99.82
Δ	10	25	50	75	100

Values of S when level of noise is equal to 44%, $c_1 = 119$, $c_2 = 120$

Conclusions

- an algorithm of recognition of numerical matrices presented
 - minimization of Lebesgue measure of united solution sets is the heuristics which the algorithm uses
 - the recognition algorithm doesn't have a learning stage and it has a quadratic computational complexity
-